

* . .

.

:

*

-1 :

-2.1 :

[2]

-1.1 :

.3.1 :

2. محاكيات القيادة *Driving Simulators*

180

(Fixed Base

.1.2

:Driving Simulators)

)

.[6]

(

()

[5]

[3 1]

[7]

² 25

[8]

(Motion

.2.2

:Base Driving Simulators)

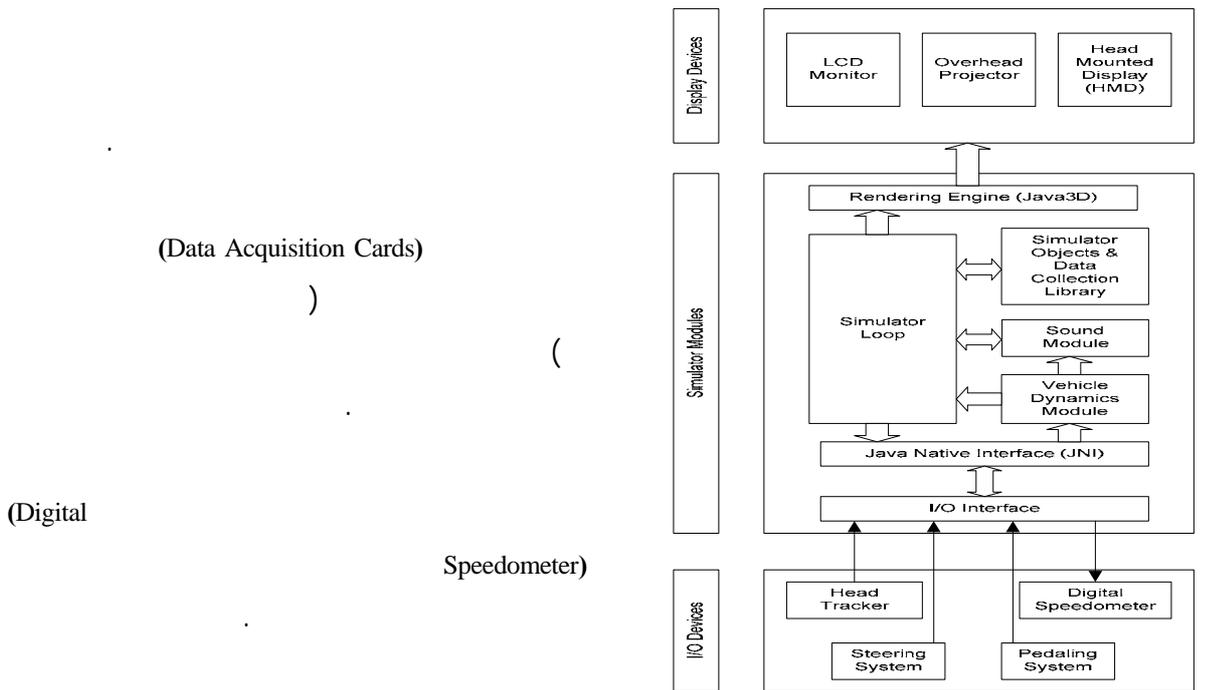
.3

:

(1)

250

45



1

(Data Acquisition Cards)
)
(
(Digital
Speedometer)

(Steering (Pedaling System)
(Head Tracking System)
.System)

()

.(3D Engine) "

: .1.3

(Head-

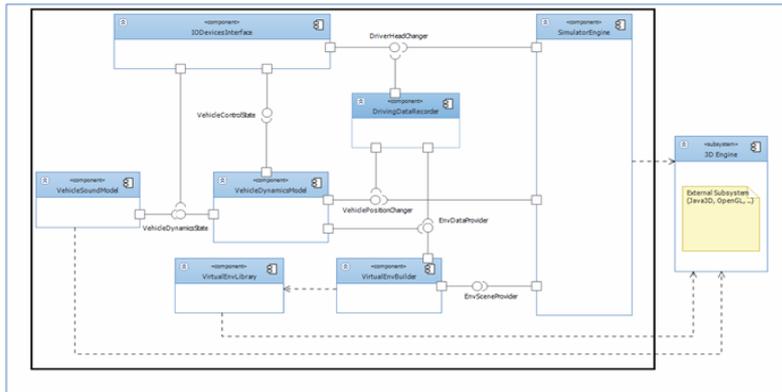
mounted Display)

()

.2.3

6 .(Head tracker)
3 3

(2)



2

(provided

(required

interfaces)

.interfaces)

() .1.2.3

:IODevicesInterface Component

)

(

(Required Interface)

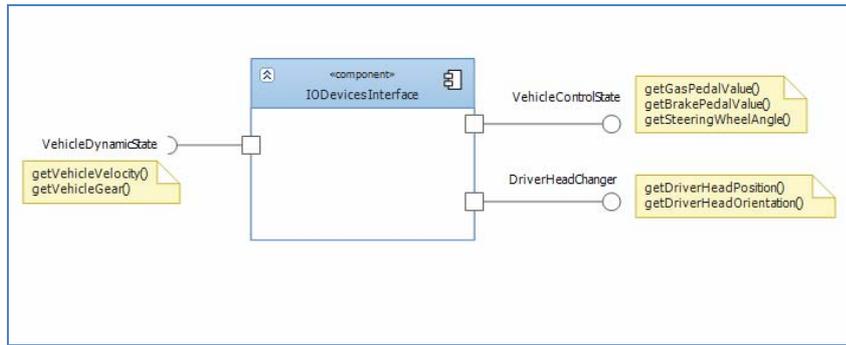
(Provided Interface)

.(3)

(

)

.1.4



() IO Devices Interface 3

:Get Driver Head Orientation •

) Vehicle Control State

.(x,y,z)

) IO Device Interfae

) Vehicle Dynamic State

) IO Device Interfae

get Vehicle

(get Vehicle Gear

Velocity

:Get Gas Pedal Value •

:get Brake Pedal Value •

:Get Steering WheelAngle •

2.2.4

Java

Java

) Driver Head Changer

) IODeviceInterfae

java native interface (JNI)

(Java)

C++

C

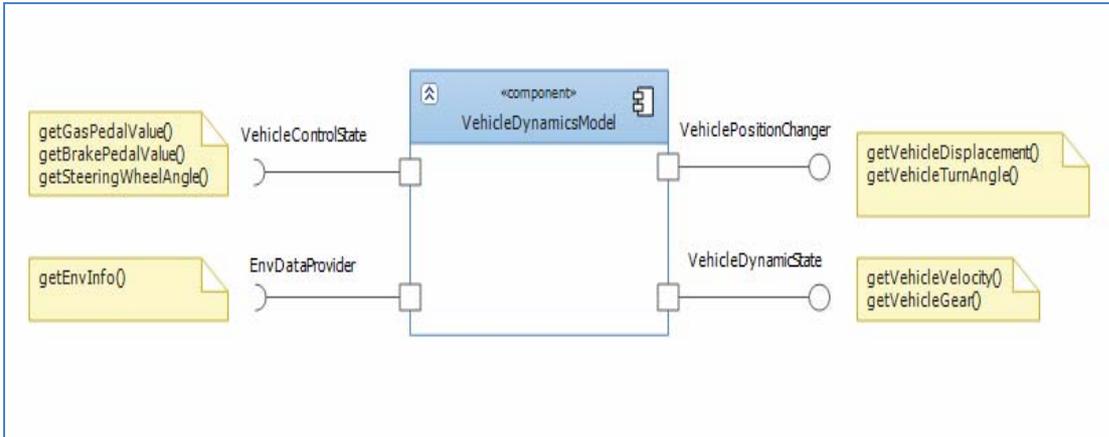
(Dynamic Link

Libraries)

:Get Driver Head Position •

native methods

(x,y,z)



```

classDiagram
    class VehicleDynamicsModel {
        <<component>>
    }
    class VehicleControlState {
        +getGasPedalValue()
        +getBrakePedalValue()
        +getSteeringWheelAngle()
    }
    class EnvDataProvider {
        +getEnvInfo()
    }
    class VehiclePositionChanger {
        +getVehicleDisplacement()
        +getVehicleTurnAngle()
    }
    class VehicleDynamicState {
        +getVehicleVelocity()
        +getVehicleGear()
    }
    VehicleDynamicsModel -- VehicleControlState
    VehicleDynamicsModel -- EnvDataProvider
    VehicleDynamicsModel -- VehiclePositionChanger
    VehicleDynamicsModel -- VehicleDynamicState
  
```

() **Vehicle Dynamics Model** 4

:Get Vehicle Gear •) Vehicle Position Changer

:(

) Vehicle Control State) Vehicle Dynamics Model

:(

IO Devices Interface (

Vehicle .1.2.4 :

() Dynamics Model :Get Vehicle Displacement •

) Env Data Provider :Get Vehicle TurnAngle •

:(

) Vehicle Dynamics Model) Vehicle Dynamic State

() Vehicle Dynamics Model

(..) (

6.2.4 :

:Get Vehicle Velocity •

Vehicle () .3.2.3

:Sound Model Component

[4]

(5)

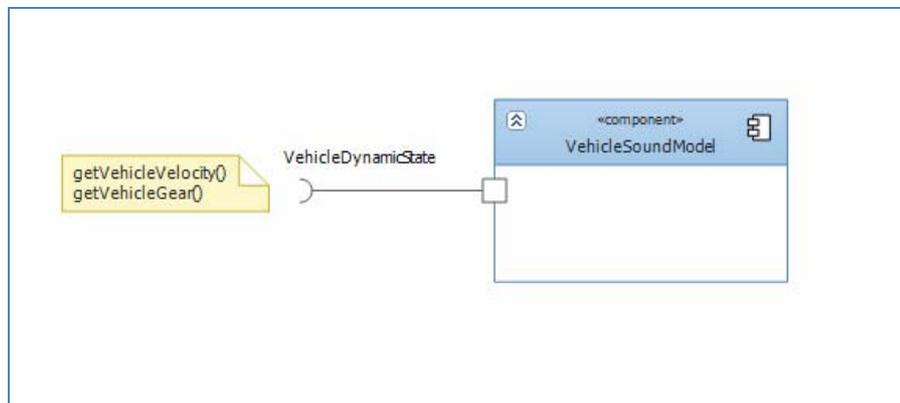
() Vehicle Dynamic State

) Vehicle Dynamics Model

.2.2.4

()

.(



() Vehicle Sound Model

.5

Simu lator

() .4.2.3

:Engine Component

:(6)

(infinite loop)

) Driver Head Changer

:(

IODevices Interface

(simulator cycle)

()

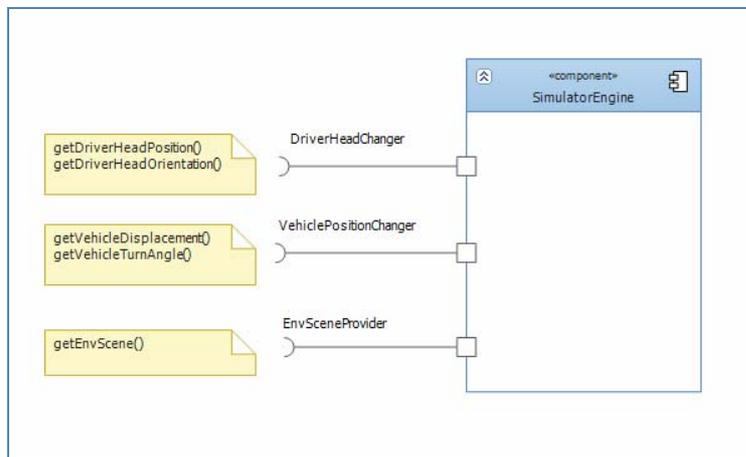
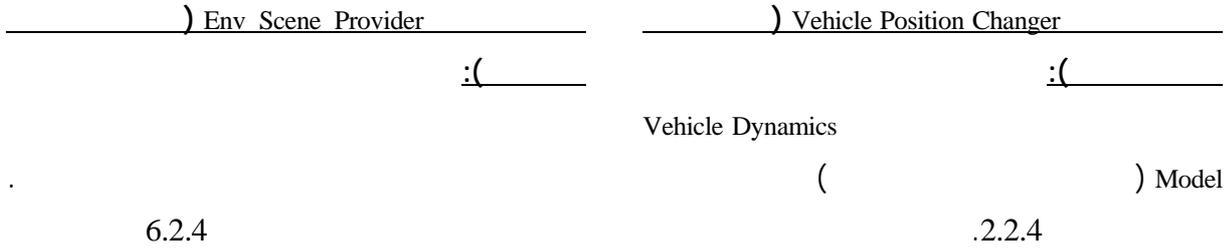
.1.2.4

(number of frames

per second)

OpenGL Java3D

(view object)



(Simulator Engine 6

: .2

(view object)

: .3

: .4

:Virtual Env

() .5.2.3
:Library Component

: .5

: .1

OpenGL Java3D

Virtual Env

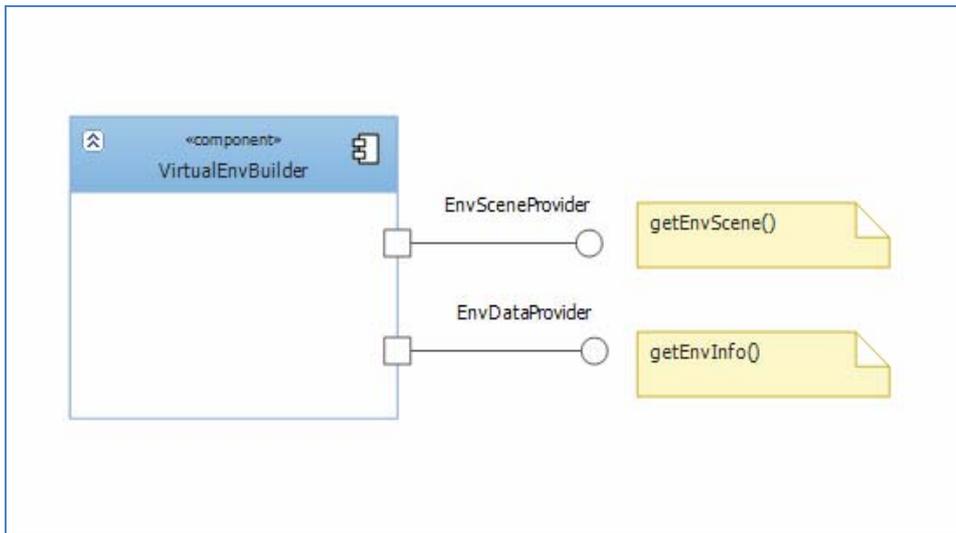
.() Library

Virtual () .6.2.3

OpenGL Java3D

:Env Builder Component

.(7)



() Virtual Env Builder

7

) Env Data Provider

) Env Scene Provider

:(

:(

(tree)

(graph)

(root node)

:get Env Scene •

(Rendering)

(tree)

(graph)

.3 (root node)

.4 :

.5 :getEnvInfo •

.6 .

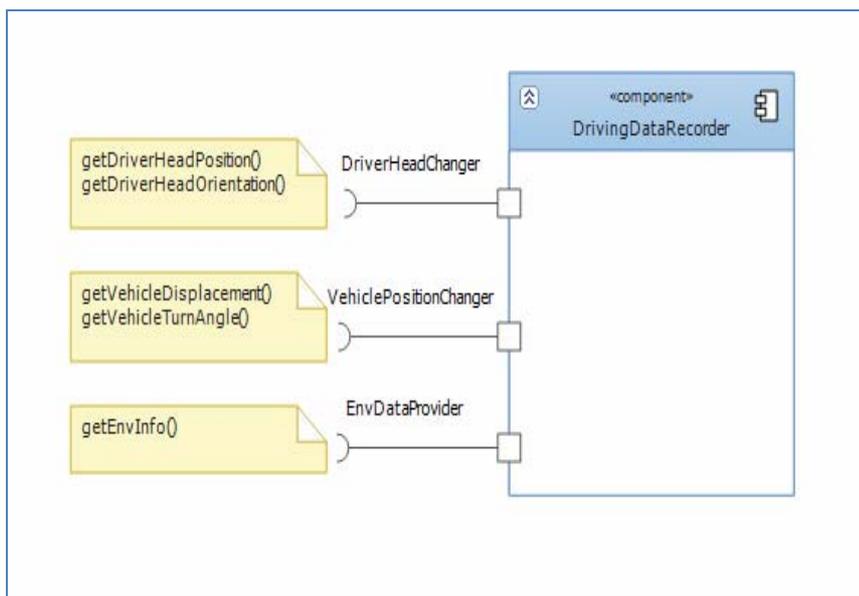
.7 **Driving** () .7.2.3

:Data Recorder Component

.(8)

.1

.2



() Driving Data Recorder

8

.4

(Provided Interfaces)

(Required Interfaces)

.5

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